

Steps for Completing the Linear Transformation Box

11-19-06

P1

Given a $V^S V$ with 2 or 3 given bases and given a $V^B W$ " " " " " and given a transformation $T: V \rightarrow W$ in some form from which we can find how one of the bases of V is associated with a basis of W , we wish to describe how to transform $v \in V$ to $T(v)$ in W and vice versa

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 ① Rule
 ② Basis
 ③ Matrix

1. Proclaim one basis of V to be the standard basis S of V ,
Name the other one or two bases of V B and D
2. Proclaim one basis of W to be the standard basis U ,
Name the other one or two bases of W E and F
3. Since S is a basis, write $B_1 = lc S$'s. Name the coeffs $[B_1]_S$, a column matrix
Since S is a basis, write $B_n = lc S$'s. Name the coeffs $[B_n]_S$, a column matrix
4. Form and name the augmented matrix $[[B_1]_S | \dots | [B_n]_S] = B_{col}$
5. Repeat steps 3 & 4 to form D_{col}
6. Repeat steps 1, 3, 4, 5 to form E_{col} and F_{col}
7. Define $S_{col} = I_n$ and $U_{col} = I_m$
8. For each of the three bases of V define an isomorphism from V to \mathbb{R}^n
 For $v \in V$, $v = lc S$'s so name coeffs $[v]_S$
 $v = lc B$'s so name coeffs $[v]_B$
 $v = lc D$'s so name coeffs $[v]_D$
9. Repeat step 8 for $w \in W$
10. Define the isomorphisms $isoS: V \rightarrow \mathbb{R}^n: v \mapsto [v]_S$, i.e., $isoS(v) = [v]_S$,
 $isoB: \mathbb{R}^n \mapsto [v]_B$, $isoB(v) = [v]_B$,
 $isoD: \mathbb{R}^n \mapsto [v]_D$, $isoD(v) = [v]_D$
11. Repeat Step 10 for $w \in W$

(Now) $v \in V$ in \mathbb{R}^n and $w \in W$ in \mathbb{R}^m

- $$12. \text{ Note } B_1 = \text{lc } f_1 \text{ or } B_1 = [[s_1 \dots s_n]] \circ [B_1]_S \\ \vdots \\ B_n = [[s_1 \dots s_n]] \circ [B_n]_S$$

$$\text{So } [[B_1 \cdots B_n]] = [[s_1 \cdots s_n]] [([B_1]_S, \dots, [B_n]_S)] = [[s_1 \cdots s_n]] \text{ Bcal}$$

13. Repeat step 12 for Scol , Ecol , Fcol , $\text{Scol} = I_n$, $\text{Ecol} = I_m$

14. Recall also if $\mathbf{S}_j = \mathbf{T}_n$ and $\mathbf{S}_k = \mathbf{T}_m$
 14. For each of the three bases, let $v \in V$, $w \in W$,

$$r = \text{lc } S'_3 = [[S_1 \dots S_n]] \cdot [v]_S = [[S_1 \dots S_n]] \text{ Scil } [v]_S$$

$$[[B_1 \dots B_n]] \cdot [v]_B = [[\delta_1 \dots \delta_n]] \operatorname{Bod} [\sigma]_B$$

$$[\![A_1 \dots A_n]\!] \cdot [\![v]\!]_D = [\![S_1 \dots S_n]\!] \text{ Adol } [\![v]\!],$$

$$\text{So } [\vec{v}]_S = \text{Scal } [v]_S = \text{Bscal } [v]_B = \text{Lscal } [v]_D$$

15. Repeat step 14 to get

$$[w]_u = \underbrace{\text{Ucol}}_{\mathbb{F}} [w]_u = \text{Ecol} [w]_E = \text{Fcol} [w]_F$$

16. Suppose $T: V \rightarrow W$: $v \mapsto T(v) = \bar{w}$ is defined rel to S and U .

$$\left. \begin{array}{l} s_1 \mapsto T(s_1) = [[u, \dots, u_m]] \cdot [T(s_1)]_u \\ \vdots \\ s_n \mapsto \quad \quad \quad [T(s_n)]_u \end{array} \right\} \text{We form matrix } A = [[T(s_1)], \dots, [T(s_n)]]$$

- is defined rel to B and E basis

$$B_1 \mapsto T(B_1) = [[E_1 \dots E_n]] \cdot [T(B_1)]_E \quad \left. \begin{array}{c} \\ \vdots \\ \end{array} \right\} \text{We form matrix } C = [T(B_1)]_E \dots [T(B_n)]_E$$

We form matrix $G = \begin{bmatrix} [T(B_1)]_F & \cdots & [T(B_n)]_F \end{bmatrix}$

18. For any $v \in V$, we can choose any of the three bases B, S, D .

For $v \in V$ rel to B

$$\text{Isom}^{-1} C \text{ Isom}(v) \quad \text{start here}$$

$$\text{Isom}^{-1} C \text{ Isom}(\text{lc } B's)$$

$$\text{Isom}^{-1} C \text{ Isom}([B_1 \dots B_n] \cdot [v]_B)$$

$$\text{Isom}^{-1} C \text{ Isom}(v)$$

$$\underbrace{\text{Isom}^{-1} C \cdot [v]_B}_{\text{lc } E's}$$

$$\underbrace{\text{Isom}^{-1} [T(v)]_E}_{\text{lc } E's}$$

$$[[E_1 \dots E_n]] \cdot [T(v)]_E$$

lc E 's

$T(v)$

$$\text{where } C = \text{Isom}^{-1} A \text{ Isom} = T \text{ of } B^E$$

$$\text{or } C = \text{Isom}^{-1} \text{Isom} G \text{ Isom}^{-1} \text{Isom}$$

$$\text{or } C = P A P^{-1}$$