

The following program is offered as a example to be used for Program 1. Make sure to provide the INCLUDE and CONFIG statements.

```

        cblock 0x20
Delay1      ; Assign an address to label Delay1
Delay2
Display     ; define a variable to hold the display
        endc

        org 0
Start:
        bsf     STATUS,RPO      ; select Register Page 1
        movlw   0xFF            ; Make PortA all input
        movwf   TRISA           ; Make PortD all output
        clrf    TRISD           ; A2D Clock Fosc/8
        movlw   0x10            ; we want all Port A pins Analoga
        movwf   ADCON1
        movlw   0xFF            ; back to Register Page 0
        bcf     STATUS,RPO

        movlw   0x01
        movwf   ADCON0         ; configure A2D for Channel 0 (RA0), Left justified, and turn on the A2D module
MainLoop:
        nop                    ; wait 5uS for A2D amp to settle and capacitor to charge.
        nop                    ; wait 1uS
        nop                    ; wait 1uS
        nop                    ; wait 1uS
        nop                    ; wait 1uS
        bsf     ADCON0,GO_DONE  ; start conversion
        btfss   ADCON0,GO_DONE ; this bit will change to zero when the conversion is complete
        goto    $-1

        movf    ADRESH,w       ; Copy the display to the LEDs
        movwf   PORTD
        goto    MainLoop

        end

```

Figure 2 AD Assembly Program Example

Program #1: Understanding A/D Configuration and Operation

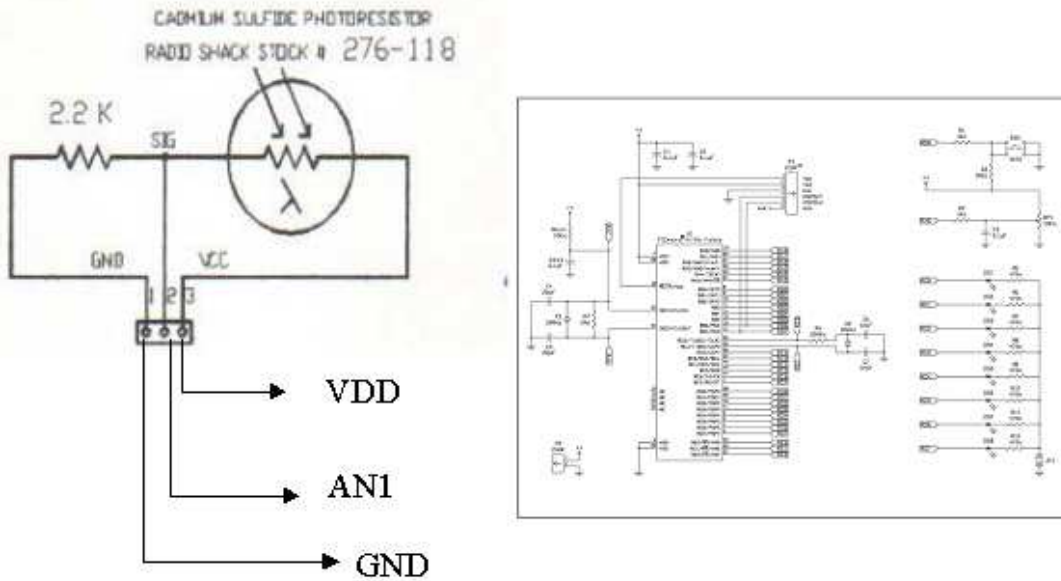
Analog to Digital Conversion is a technique frequently used by Microcontroller to measure external voltage (typically from a external sensor) and convert the incoming voltage to a digital number. The PIC supports a 10-bit A/D or count of 0 to 1023. Incoming voltages value controls the count. Use the built in pot on the board to pin AN0. Enter, built and run the following program shown above. The A/D value present at AN) is converted and displayed continuously on the LEDs.

The pot represents a simulated sensor that you can control the control the input to A/D by varying pot setting. The LEDS will represent the 8 bit high portion of the 10 bit digital A/D output count. Get a digital voltmeter and measure the voltage between the wiper and ground for each of the following digital counts. VDD represents +5VdV and the ground and AN0 pins are available.

<u>LED Output</u>	<u>Voltage</u>
00H	
2FH	
3FH	

Program#2 Hooking up the photocell sensor and recording light/dark levels

Modify program #1 to read AN1 versus AN0 and have the following circuit constructed and hooked to AN2. Have instructor verify circuit before power up. Instructor Signoff _____



The photocell varies its internal resistance based upon available light. As a result you should get a digital output for both normal and dark conditions observing the LEDs and covering and uncovering the photo sensor.

Record the two levels. You will need them for the next program.

Normal_____

Dark_____

Program #3 Implemented a Light Controlled LED

Design and implement a program, modifying what has been done so far, that uses the photocell dark condition to turn on the most significant LED and then turn off automatically the same LED when light returns to normal. You will need to use the A/D service. Write as a continuous loop. Draw out a flowchart. Demo to instructor. Instructor Signoff _____.

Program 3 Flowchart

